

OCEAN2020 Webinar

DEMONSTRATION IN THE MEDITERRANEAN SEA, NOV 2019





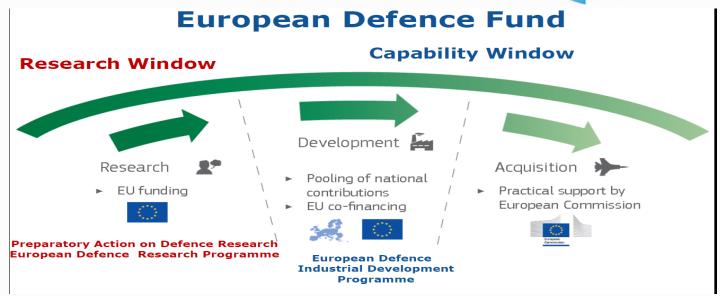


9th July 2020

OCEAN2020 Project Context



- ▶ PADR : pave the way for the Research Dimension of the European Defence Fund (EDF)
- ➤ **PADR** is launched and funded by the **European Commission**
- ➤ European Defense Agency is the implementing agency for the PADR



OCEAN2020: the PADR Project with highest budget (35.5 M€ out of 90 M€ of PADR Budget)



10 National MoDs/Navies supporting OCEAN2020

- Italian Navy
- Hellenic Navy
- Spanish Navy
- Portuguese Navy
- Lithuanian Navy
- German MoD
- Swedish Navy
- French Navy
- Polish Navy
- Royal Dutch Navy

OCEAN2020 Project Objectives



Operational objectives

- Significant improvement of **maritime Situation Awareness** through the integration of **UXS** (Unmanned Systems) with **ISTAR** (Intelligence Surveillance Target Acquisition and Reconnaissance) payload capabilities
- Interoperability by use of open architecture and recognised standards

Technical objectives

- High integration among EU countries and heterogeneous systems, demonstrated in full-scale demo
 - ✓ Mediterranean Sea demonstration in 2019
 - ✓ Baltic Sea demonstration in 2021
- Development of EU C4ISR open architecture
- Integration of EU/NATO/civil data framework
- Advanced data and information fusion techniques for shorter decision time at CMS (Combat Management System) and MOC (Maritime Operations Centre) levels
- Increased autonomy for UXS, swarm operations, cooperation of assets

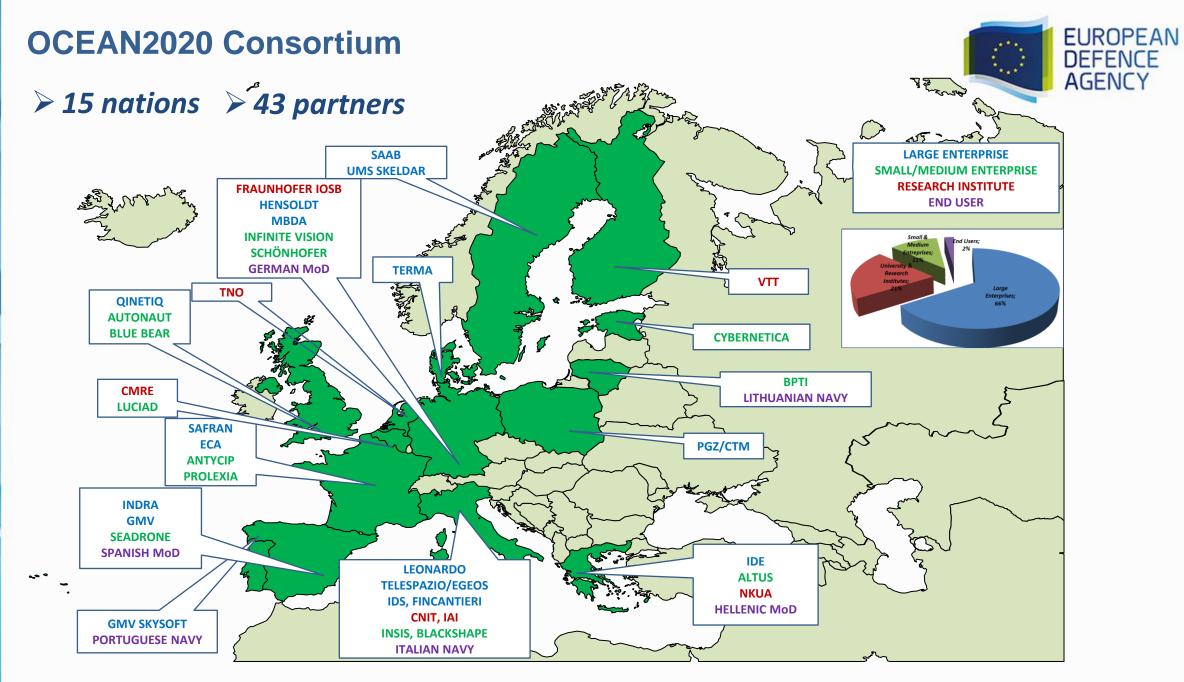
Cooperation objectives

- Diverse EU wide consortium to demonstrate large military R&T effort
- Improve market position of European defence industry in UXS
- Involve End-Users in design choices

Expected impact:

- demonstrate the potential of EU-funded research for defense applications
- boost the European industrial capacity in the military unmanned systems market

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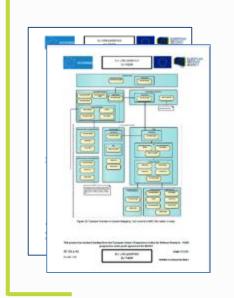
OCEAN2020 Project Activities



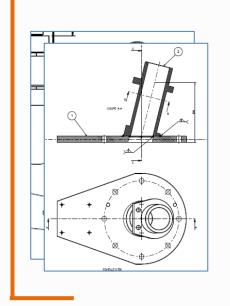
Roadmap to Mediterranean Sea Demonstration (MED SEA DEMO)



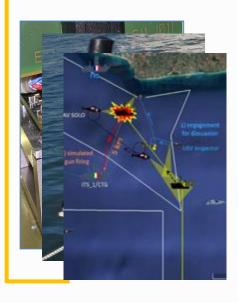




Development



Integration and trials



OCEAN2020 Unmanned Systems

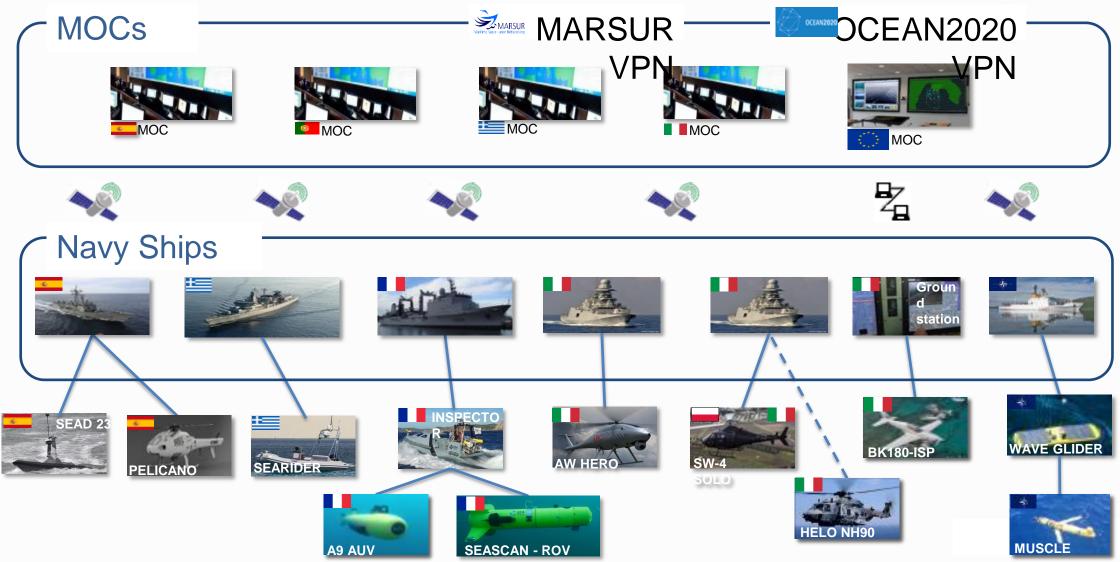




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OCEAN2020 MED SEA DEMO - SYSTEM DEPLOYMENT







EU MOC Showroom

Setup of the EU MOC Prototype





EU MOC Shipping

EU MOC Technical Room















THANK YOU FOR YOUR ATTENTION



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OCEAN2020 Webinar MEDITERRANEAN SEA DEMONSTRATION





20-21 November 2019



NAVAL

UNITS Italian Frigate 1 (Martinengo, FREMM)

Italian Frigate 2 (Fasan, FREMM)

Spanish Frigate (Santa Maria)

Hellenic Frigate (Limnos)

French BCR (Var, Durance class)

Italian MTC (Gorgona Class) - suspect vessel



Italian NH90 Helicopter



LOCATIONS

AREA OF OPERATIONS:

within the Gulf of Taranto

Taranto NAVAL BASE (Italian Navy)

Grottaglie MILITARY AIRPORT

MARITIME OPERATION CENTERS

EU MOC Prototype: Bruxelles (in EDA)

IT MOC: Rome

ES MOC: Cartagena

HE MOC: Athens

PT MOC: Lisbon

UAV UNMANNED AIR VEHICLES

Leonardo AW Hero Leonardo SW-4 Solo **INDRA** Pelicano Blackshape Bk180-ISP





USV UNMANNED **SURFACE VEHICLES**

ECA Inspector IDE SeaRider Seadrone SEAD-23

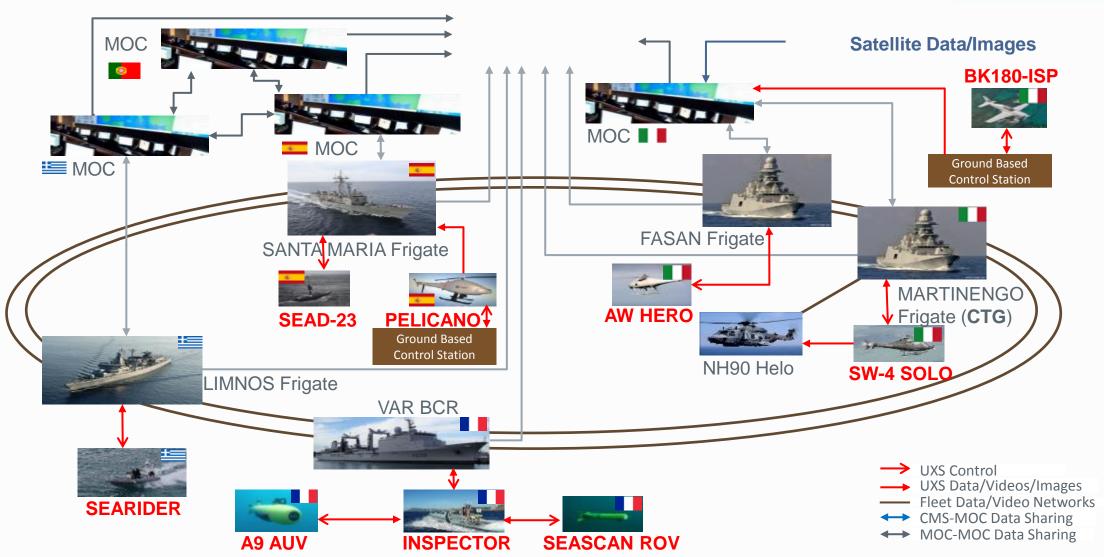
UUV <u>UNMANNED</u> **UNDERWATER VEHICLES**

ECA AUV A9 **ECA ROV Seascan**



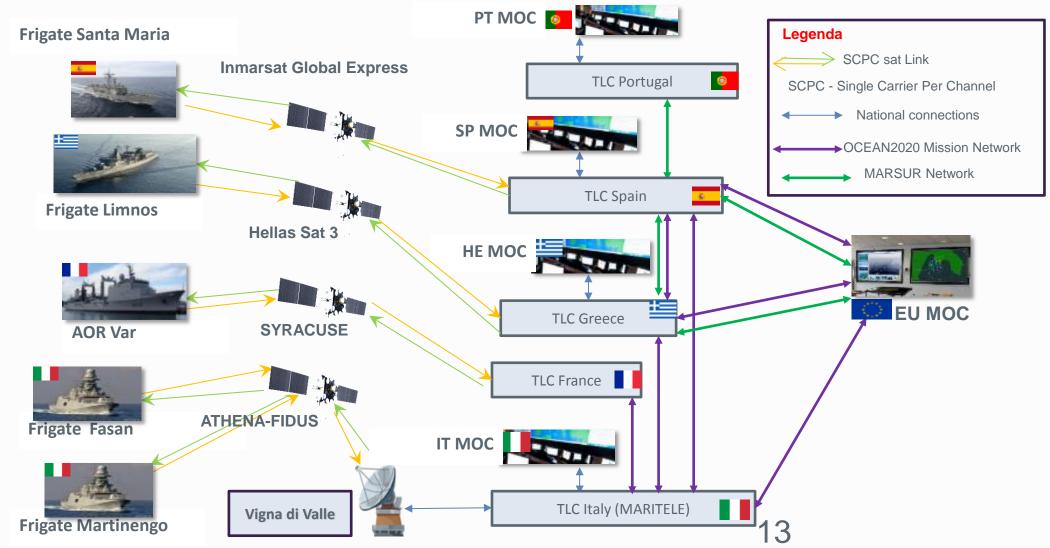
System Configuration for Mediterranean Sea Demo





Ships and MOCs Networking





OCEAN2020 MED SEA DEMO -Scenario #1



Threatening Vessel Interdiction

Phase 0 Scenario preparation / Persistent Surveillance



Cosmo Sky Med (Earth Observation Satellite)

Phase 1 Alert for anomaly detection



Cosmo Sky Med (Earth Observation Satellite)

Phase 2 Resource tasking and area search



Phase 3 Localisation, classification and identification









Phase 4 Surface engagement (simulated)





Phase 5 UW localisation of the threat remains





OCEAN2020 MED SEA DEMO -Scenario #2



Mine Laying Vessel Interception before an Amphibious Operation

Phase 0 Scenario preparation / Intelligence received



Phase 1 Suspect vessel leaves the harbour and is detected by USV and UAV







Phase 2 Covert localisation and tracking with UAV







Phase 3 Mines are released by the vessel





Phase 4 Boarding with UAV support







Phase 5 Mines localisation and identification with UUV



Maritime Situation Awareness and ISTAR capabilities at Sea





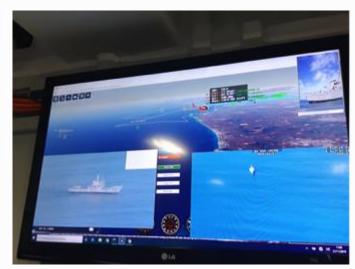
ROV SEASCAN Control Station on board French BCR Var



UAV AW Hero Control Station on board Italian Frigate Fasan



USV Sea Rider Control Station on board Hellenic Frigate Limnos







Tactical Situation with 3D view and videos from Unmanned Systems displayed on board Italian Frigate Martinengo

Maritime Situation Awareness and ISTAR capabilities ashore

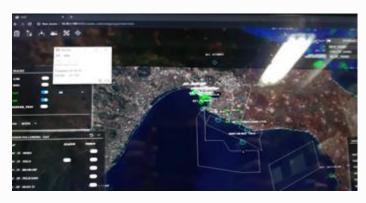




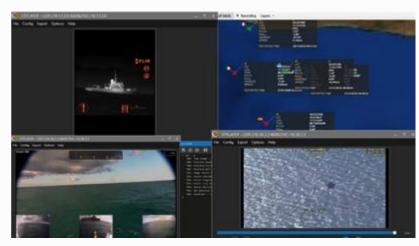
BK180-ISP Ground Station at Grottaglie Military Airport



Boarding phase of Scenario 2 displayed at IT MOC in Rome



Tactical Situation displayed at EU MOC Prototype in Bruxelles



Tactical Situation and videos from Unmanned Systems displayed at Hellenic MOC in Athens





Tactical Situation and Video Wall with videos from Unmanned Systems displayed at Spanish MOC in Cartagena

OCEAN2020 MED SEA DEMO - Achievements



Improvement of maritime situational awareness

- Surveillance information generated by UxVs
- Integration with CMS and MOC

Extending range and performance of maritime ISTAR capability

UxS Payload (EO/IR, Radar, AIS, Sonar, etc.)

Achieving EU-NATO interoperability

Adoption of NATO interoperability standards

Technical Innovation

- Integration of EU multi-countries, multi-producers, multi-domain manned and unmanned systems in real operational environment
- Effectiveness of an interoperable system-of-systems

Impact Making

- Effective model of pan-European Cooperation
- Efficient and Effective Defence Investments
- Future joint R&T and post R&T Activities

Effective Engagement of End-Users



































































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